Physics 2A Equation Sheet

| $\Delta \vec{r}=\vec{r}_{f}-\vec{r}_{i}$ | Displacement |
| :---: | :---: |
| $\vec{v}=\frac{\Delta \vec{r}}{\Delta t}$ | Average velocity |
| $\vec{v}=\frac{d \vec{r}}{d t}$ | Instantaneous velocity |
| $\vec{a}=\frac{\Delta \vec{v}}{\Delta t}$ | Average acceleration |
| $\vec{a}=\frac{d \vec{v}}{d t}=\frac{d^{2} \vec{r}}{d t^{2}}$ | Instataneous acceleration |
| $v=v_{o}+a t$ | Velocity as function of time |
| $x=x_{o}+v_{o} t+(1 / 2) a t^{2}$ | Position as function of time |
| $v^{2}=v_{o}^{2}+2 a\left(x-x_{o}\right)$ | Velocity as function of position |
| $x=x_{o}+\left(\frac{v_{o}+v}{2}\right) t$ | Position as function of velocity and time |
| $a_{r}=\frac{v^{2}}{r}$ | Radial (centripetal) acceleration |
| $\sum \vec{F}=m \vec{a}$ | Newton's $2^{\text {nd }}$ Law |
| $w=m g$ | Weight of a body |
| $f_{k}=\mu_{k} N$ | Kinetic friction force |
| $f_{s} \leq \mu_{s} N$ | Static frictional force |
| $W=\vec{F} \bullet s=F s \cos \theta$ | Work done by constant force |
| $F_{s}=-k x$ | Spring force (Hooke's Law) |
| $W_{s}=(1 / 2) k x_{i}^{2}-(1 / 2) k x_{f}^{2}$ | Work done by spring force |
| $W_{\text {applied }}=-W_{\text {s }}$ | Work done by applied force |
| $K=(1 / 2) m v^{2}$ | Kinetic energy |
| $W_{\text {net }}=K_{f}-K_{i}=\Delta K$ | Work-Energy Theorem |
| $P_{\text {ave }}=\frac{\Delta W}{\Delta t}$ | Average power |
| $P=\frac{d W}{d t}$ | Instantaneous power |
| $P=\vec{F} \bullet \vec{v}=F v \cos \theta$ | Instantaneous power |
| $U_{g}=m g y$ | Gravitational PE Function (constant g) |
| $U_{s}=(1 / 2) k x^{2}$ | Elastic PE Function |
| $E_{\text {mech }}=K+U$ | Total Mechanical Energy |


| $W_{n c}=\Delta K+\Delta U$ | Work by non-conservative forces |
| :---: | :---: |
| $\mathrm{K}_{\mathrm{i}}+\mathrm{U}_{\mathrm{i}}=\mathrm{K}_{\mathrm{f}}+\mathrm{U}_{\mathrm{f}}$ | Conservation of Mechanical Energy |
| $\vec{P}=M \vec{V}$ | Linear Momentum |
| $\sum \vec{F}_{e x t}=\frac{d \vec{P}}{d t}$ | Newton's $2^{\text {nd }}$ Law |
| $\vec{I}=\sum \vec{F}_{e x t}\left(t_{2}-t_{1}\right)$ | Impulse due to a constant net force |
| $I=\vec{p}_{2}-\vec{p}_{1}=\Delta \vec{p}$ | Impulse-Momentum Theorem |
| $v_{2 f}-v_{1 f}=-\left(v_{2 i}-v_{1 i}\right)$ | Relative velocities in an elastic collision |
| $s=r \theta$ | Arc length |
| $\bar{\omega}=\frac{\Delta \theta}{\Delta t}$ | Average Angular Speed |
| $\omega=\frac{d \theta}{d t}$ | Instantaneous Angular Speed |
| $\bar{\alpha}=\frac{\Delta \omega}{\Delta t}$ | Average angular acceleration |
| $\alpha=\frac{d \omega}{d t}=\frac{d^{2} \theta}{d t^{2}}$ | Instantaneous angular acceleration |
| $\theta=\theta_{o}+\omega_{o} t+\frac{1}{2} \alpha t^{2}$ | Angular position as function of time |
| $\omega=\omega_{o}+\alpha t$ | Angular speed as function of time |
| $\omega^{2}=\omega_{o}^{2}+2 \alpha\left(\theta-\theta_{o}\right)$ | Angular speed as function of angular position |
| $\theta=\theta_{o}+\left(\frac{\omega_{o}+\omega}{2}\right) t$ | Angular position as function of angular speed and time |
| $\nu_{t}=r \omega$ | Tangential speed |
| $a_{t}=r \alpha$ | Tangential acceleration |
| $a_{r}=\frac{v^{2}}{r}=r \omega^{2}$ | Radial (centripetal) acceleration |
| $I=\sum m_{i} r_{i}^{2}$ | Moment of Inertia for System of Particles |
| $I_{p}=I_{c m}+M d^{2}$ | Parallel-Axis Theorem |
| $K_{R}=\frac{1}{2} I \omega^{2}$ | Rotational kinetic energy |
| $\vec{\tau}=\vec{r} \times \vec{F}$ | Definition of Torque |
| $\sum \tau=I \alpha$ | Newton's 2 ${ }^{\text {nd }}$ Law for Rotation |
| $W=\tau \Delta \theta$ | Work Done by a constant Torque |



